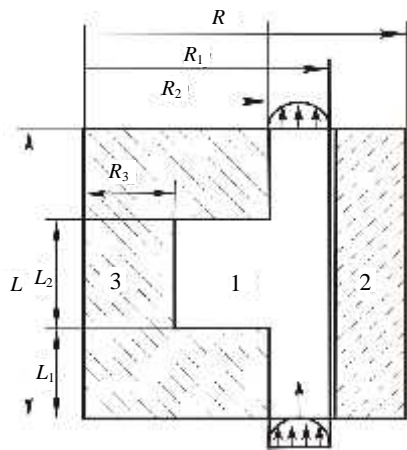




536.2



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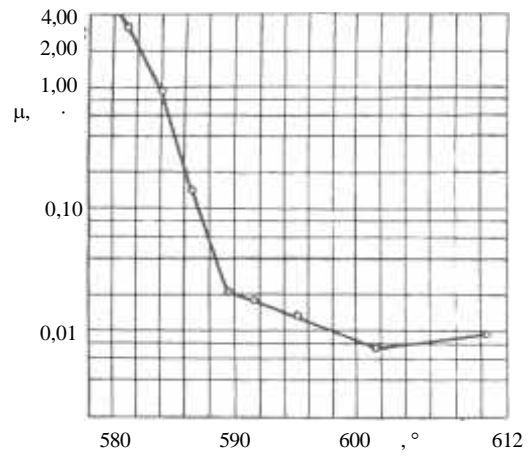
$= (T).$

$(. 2)$

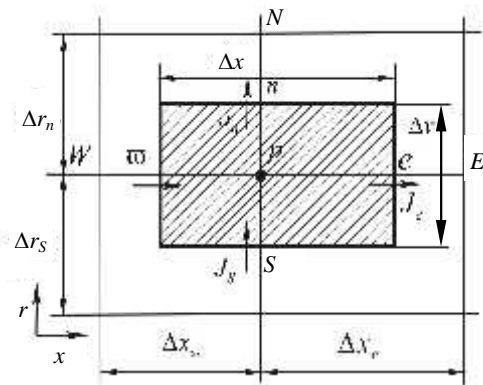
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$(. 3),$



. 2.



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 (u, v,
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 $L \times R$ (. 1).

$$\rho c \left[\frac{\partial T}{\partial t} + \frac{1}{r} \left(\frac{\partial r v_x T}{\partial x} + \frac{\partial r v_r T}{\partial r} \right) \right] = \frac{1}{r} \left[\frac{\partial}{\partial x} \left(r \lambda \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial r} \left(r \lambda \frac{\partial T}{\partial r} \right) \right]. \quad (1)$$

$$\frac{\partial r v_x T}{\partial x} + \frac{\partial r v_r T}{\partial r} = 0.$$

•

$$\frac{\partial v_r}{\partial r} + \frac{\partial v_r}{\partial x} = 0; \quad (2)$$

• r

$$\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + v_x \frac{\partial v_r}{\partial x} = -\frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{1}{r} \frac{\partial}{\partial r} r \tau_{rr} + \frac{\partial}{\partial x} \tau_{rx} = \frac{\tau_{\varphi\varphi}}{r}; \quad (3)$$

•

$$\frac{\partial v_x}{\partial t} + v_r \frac{\partial v_x}{\partial r} + v_x \frac{\partial v_x}{\partial x} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{1}{r} \frac{\partial}{\partial r} r \tau_{rx} + \frac{\partial}{\partial x} \tau_{xx}. \quad (4)$$

(3), (4),

$$\tau_{rx} = \mu \left(\frac{\partial v_r}{\partial x} + \frac{\partial v_x}{\partial r} \right); \quad \tau_{rr} = 2 \mu \frac{\partial v_r}{\partial r}; \quad (5)$$

$$\tau_{xx} = 2\mu \frac{\partial v_x}{\partial x}; \quad \tau_{\varphi\varphi} = 2\mu \frac{v_r}{r}.$$

$$\mu \quad (5)$$

:

$$\frac{\partial ru}{\partial x} + \frac{\partial rv}{\partial r} = 0; \quad (6)$$

$$\frac{\partial v}{\partial t} + \frac{1}{r} \left(\frac{\partial ruv}{\partial x} + \frac{\partial rv^2}{\partial r} \right) = \frac{1}{r} \left[\frac{\partial}{\partial x} \left(r\mu \frac{\partial v}{\partial x} \right) + \frac{\partial}{\partial r} \left(r\mu \frac{\partial v}{\partial r} \right) \right] + Q_v; \quad (7)$$

$$\frac{\partial u}{\partial t} + \frac{1}{r} \left(\frac{\partial ru^2}{\partial x} + \frac{\partial ruv}{\partial r} \right) = \frac{1}{r} \left[\frac{\partial}{\partial x} \left(r\mu \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial r} \left(r\mu \frac{\partial u}{\partial r} \right) \right] + Q_u, \quad (8)$$

$$Q_v \quad Q_u \quad :$$

$$Q_v = -\frac{\partial p}{\partial r} + \frac{\partial u}{\partial r} \frac{\partial v}{\partial r} + \frac{\partial u}{\partial x} \frac{\partial u}{\partial r}; \quad (9)$$

$$Q_u = -\frac{\partial p}{\partial x} + \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial u}{\partial r} \frac{\partial v}{\partial x}.$$

$$(5)...(9)$$

$$(\bar{x}, \bar{r}) = (x, r)/R; \quad u = v_x/u_0; \quad v = v_r/u_0; \quad (10)$$

$$\bar{t} = tu_0/R_1; \quad \bar{\mu} = \mu/(\rho_f u_0 R_1); \quad \bar{p} = p/(\rho_f u_0^2),$$

$$(6)...(10)$$

$$\Theta = (T - T_\infty)/T_\infty, \quad T - \quad (1)$$

$$\rho u_0 R_1 c \left[\frac{\partial \Theta}{\partial t} + \frac{1}{r} \left(\frac{\partial ru\Theta}{\partial x} \right) \right] = \frac{1}{r} \left[\frac{\partial}{\partial x} \left(r\lambda \frac{\nabla \Theta}{\partial x} \right) + \frac{\partial}{\partial r} \left(r\lambda \frac{\partial \Theta}{\partial r} \right) \right]. \quad (11)$$

$$= T_{01}.$$

$$(7), (8)$$

$$\partial u / \partial t = 0,$$

$$- T_{01}$$

$$(6), (8), (11)$$

$$a \frac{\partial}{\partial t} + b \frac{1}{\bar{d}} \left(\frac{\partial ru}{\partial x} + \frac{\partial rv}{\partial r} \right) = d \frac{1}{r} \left[\frac{\partial}{\partial x} \left(r \frac{\partial}{\partial x} \right) + \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) \right] Q. \quad (12)$$

$$= 1, u, v, \Theta.$$

$$(11) \quad \rho, \mu, R, \lambda - \text{Re} = \rho_f u_0 R_1 / \mu$$

$$\text{Pr} = c_p \mu / \lambda$$

(6)...(11)

$$2 \left(\begin{matrix} t = 0 \\ r = 1 \end{matrix} \right) = T_{02}; \quad 1 \left(\begin{matrix} r = 1 \\ x = 0 \end{matrix} \right) = T_{01}; \quad 3 \left(\begin{matrix} r = 1 \\ x = L \end{matrix} \right) = T_{03}.$$

$$-\lambda \frac{\partial T}{\partial r} = \alpha(T - T_\infty),$$

$$\frac{\partial T}{\partial r} = 0.$$

$$r = 1$$

$$\frac{\partial \Theta}{\partial r} = \text{Bi} \Theta;$$

$$r = 0$$

$$\frac{\partial \Theta}{\partial r} = 0,$$

$$\text{Bi} = \frac{\alpha R}{\lambda}; \lambda -$$

$$x = L$$

$$\ll \gg. \quad x = 0$$

(12),

(12)

$$\frac{\partial}{\partial t} + \frac{1}{r} \left(\frac{\partial I_x}{\partial x} + \frac{\partial I_r}{\partial r} \right) = Q, \quad (13)$$

$$I_x \quad I_r - \left(\begin{matrix} \text{ } \end{matrix} \right),$$

$$I_x = r \left(u - \frac{\partial}{\partial x} \right);$$

$$I_r = r \left(v - \frac{\partial}{\partial r} \right),$$

= /b -

, b -

. 3

, , w, s

, N, W, S.

(13)

$$-\frac{p}{t} r_p x r + [(I_{xe} - I_{xw}) r + (I_{rn} - I_{rs}) x] = rQ \quad x r, \quad (14)$$

$$\frac{I_{xe} I_{xw} I_{rn} I_{rs}}{p} -$$

$$(F_e - F_w)\Delta r + (F_n - F_s)\Delta x = 0, \quad (15)$$

$F_e, F_w, F_n, F_s -$

: $F_e = r_p u_e; F_w = r_p u_w; F_n = r_n v_n;$

$F_s = r_s v_s; \Delta x, \Delta r -$

$$(15) \quad p \quad (14),$$

$$-\frac{p}{\Delta t} r_p \Delta x \Delta r +$$

(16)

$$+ \{[(I_e - F_e) - (I_w - F_w)]\Delta r + [(I_n - F_n) - (I_s - F_s)]\Delta x = r_p Q \Delta x \Delta r.$$

(16)

$$I_e = A_e + B_p.$$

(16)

$$C_p = C_E + C_W + C_N + C_S + S, \quad (17)$$

$$C_p = C_E + C_W + C_N + C_S + \frac{r_p \Delta x \Delta r}{\Delta t};$$

$$S = \left(Q + \frac{0}{t} \right) r_p \Delta x \Delta r.$$

, w, C_N, C_S

:

$$\begin{aligned} C_E &= T_e(F_e + |F_e|) + |L_e| - L_e; \\ C_W &= T_w(F_w + |F_w|) + |L_w| + L_w; \\ C_N &= T_n(F_n + |F_n|) + |L_n| - L_n; \\ C_S &= T_s(F_s + |F_s|) + |L_s| + L_s, \end{aligned} \tag{18}$$

$$L_e = u_e r_p \Delta r; \quad L_w = u_w r_p \Delta r; \quad L_n = v_n r_n \Delta x; \quad L_s = v_s r_s \Delta x;$$

$$T_e = r_p \frac{\Delta r}{\Delta x_e}; \quad T_w = r_p \frac{\Delta r}{\Delta x_w}; \quad T_n = r_n \frac{\Delta x}{\Delta r_n};$$

$$T_s = r_s \frac{\Delta x}{\Delta r_s}.$$

$$\Delta x_e, \Delta x_w, \Delta r_n, \Delta r_s, - \quad ; \quad \Delta x, \Delta r -$$

F (18)

$$: F = 0,5(1 - |L|/T) -$$

$$; F = 0,5(1 - 0,1|L|/T)^5 -$$

$$Pe_e = L_e/T_e = u_e \Delta x_e /$$

$$-2 \leq Pe \leq 2 ($$

)

$$\partial / \partial x$$

$$\left(\frac{E - p}{u_E + u_0} \right) / \Delta x_e,$$

$$> 2 \quad < -2$$

> 10

(11). , , . (11)

(11) (17), -
 , -
 : , -
 $C_E = T_e; C_W = T_w; C_N = T_n; C_S = T_s.$ (19)

$a, b = /b$ (12)

$Q = Q /b$ (18).

1., 1967. - 600 .
2., 1979. - 323 .
3., 1989. - 203 .
4., 1977. - 264 .

20.04.2005